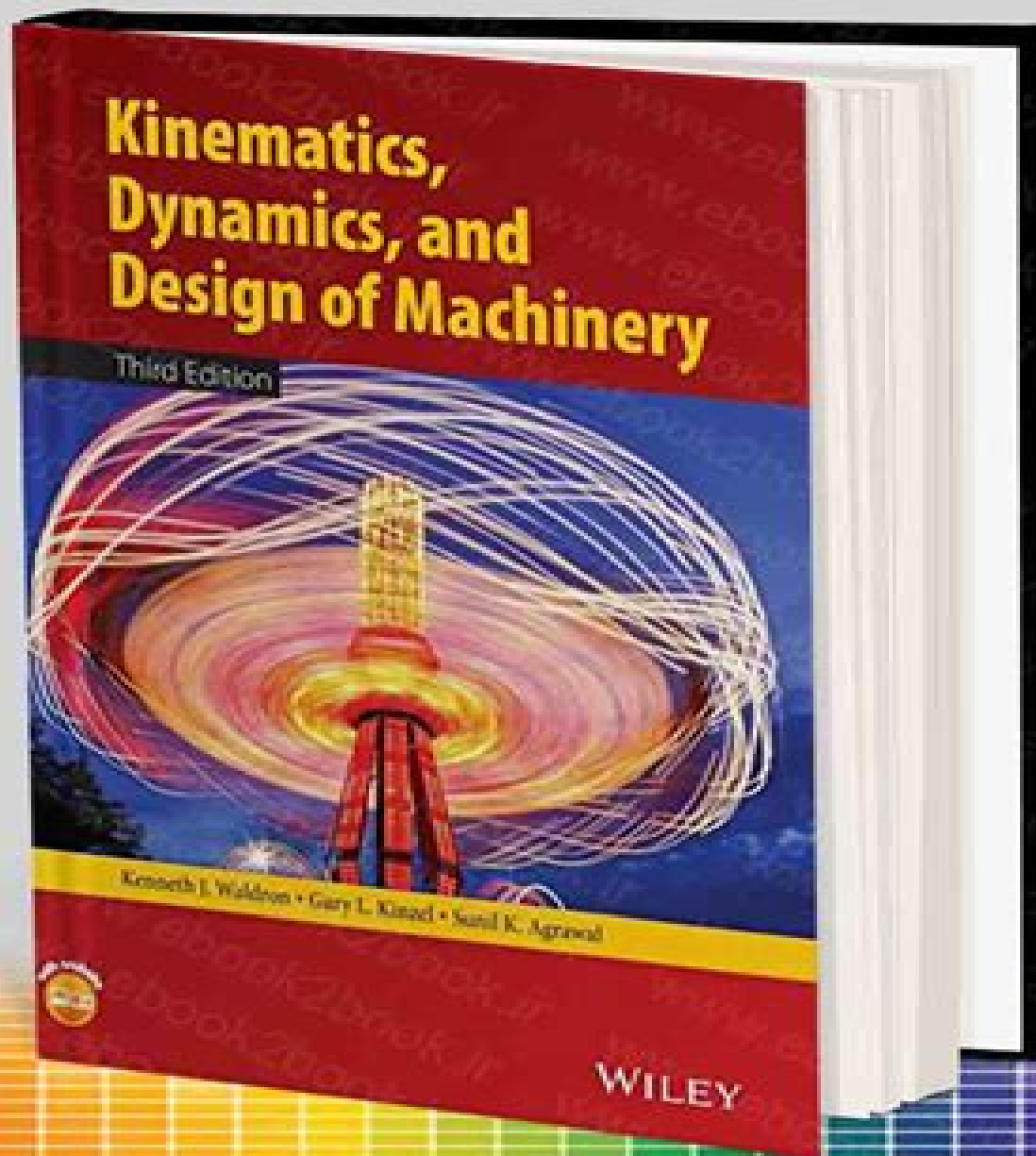


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loops are also treated in detail In the third edition planar multibody systems are presented in a separate chapter to facilitate the transition from mass point systems to spatial multibody systems **Scientific and Technical Books in Print** ,1972

Dynamics of the Rigid Solid with General Constraints by a Multibody Approach Nicolae Pandrea,Nicolae-Doru Stanescu,2016-05-03 Covers both holonomic and non holonomic constraints in a study of the mechanics of the constrained rigid body Covers all types of general constraints applicable to the solid rigid Performs calculations in matrix form Provides algorithms for the numerical calculations for each type of constraint Includes solved numerical examples Accompanied by a website hosting programs *Mechanical Engineering News* ,1978 **Information Sources in Engineering** L. J. Anthony,1985 Good No Highlights No Markup all pages are intact Slight Shelfwear may have the corners slightly dented may have slight color changes slightly damaged spine Kinematics and Dynamics of Planar Machinery Burton Paul,1979

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