



main.py | **main.py:14** | Line 14:5 | Line 14

```
name = 0000000000000000: error = 1: break
name = 0000001000000000: error = 2: break
name = 0000002000000000: error = 3: break
name = 0000003000000000: error = 4: break
name = 0000004000000000: error = 5: break
name = 0000100000000000: error = 6: break
name = 0000100000000000: error = 7: break
name = 0000100000000000: error = 8: break
name = 0000100000000000: error = 10: break
name = 0000100000000000: error = 11: break
name = 0000100000000000: error = 12: break
name = 0000100000000000: error = 13: break
name = 0000100000000000: error = 14: break
```

```
}
```

```
int rotateError = error - lastError;
lastError = error;
int moveLeft = (int) (error * 10) + (rotateError * 10 + 1);
int moveRight = 10 + moveLeft;
int maxSpeed = 10 + moveRight;
int minSpeed = 0;
int maxSpeed = 10;
moveLeft = maxmax(moveLeft, minSpeed, maxSpeed);
moveRight = maxmax(moveRight, minSpeed, maxSpeed);
return(moveLeft, moveRight);
```

```
}
```

# Line Follower Aurdino Pid Code

**Avirup Basu**



## **Line Follower Aurdino Pid Code:**

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