

Matrix Mathematics

Matrix Mathematics Theory Facts And Formulas Second Edition

Petko H Petkov



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Scalar, Vector, and Matrix Mathematics Dennis S. Bernstein, 2018-02-27 The essential reference book on matrices now fully updated and expanded with new material on scalar and vector mathematics Since its initial publication this book has become the essential reference for users of matrices in all branches of engineering science and applied mathematics In this revised and expanded edition Dennis Bernstein combines extensive material on scalar and vector mathematics with the latest results in matrix theory to make this the most comprehensive current and easy to use book on the subject Each chapter describes relevant theoretical background followed by specialized results Hundreds of identities inequalities and facts are stated clearly and rigorously with cross references citations to the literature and helpful comments Beginning with preliminaries on sets logic relations and functions this unique compendium covers all the major topics in matrix theory such as transformations and decompositions polynomial matrices generalized inverses and norms Additional topics include graphs groups convex functions polynomials and linear systems The book also features a wealth of new material on scalar inequalities geometry combinatorics series integrals and more Now more comprehensive than ever Scalar Vector and Matrix Mathematics includes a detailed list of symbols a summary of notation and conventions an extensive bibliography and author index with page references and an exhaustive subject index Fully updated and expanded with new material on scalar and vector mathematics Covers the latest results in matrix theory Provides a list of symbols and a summary of conventions for easy and precise use Includes an extensive bibliography with back referencing plus an author index

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Matrix Computations Gene H. Golub, Charles F. Van Loan, 2013-02-15 A comprehensive treatment of numerical linear algebra from the standpoint of both theory and practice The fourth edition of Gene H Golub and Charles F Van Loan s classic is an essential reference for computational scientists and engineers in addition to researchers in the numerical linear algebra community Anyone whose work requires the solution to a matrix problem and an appreciation of its mathematical properties will find this book to be an indispensable tool This revision is a cover to cover expansion and renovation of the third edition It now includes an introduction to tensor computations and brand new sections on fast transforms parallel LU discrete Poisson solvers pseudospectra structured linear equation problems structured eigenvalue problems large scale SVD methods polynomial eigenvalue problems Matrix Computations is packed with challenging problems insightful derivations and pointers to the literature everything needed to become a matrix savvy developer of numerical methods and software The second most cited math book of 2012 according to MathSciNet the book has placed in the top 10 for since 2005

Mathematics by Experiment Jonathan Borwein, David Bailey, 2008-10-27 This revised and updated second edition maintains the content and spirit of the first edition and includes a new chapter Recent Experiences that provides examples of experimental mathematics that have come to light since the publication of the first edition in 2003 For more examples and insights Experimentation in Mathematics Computational P

The Numerical Jordan Form Petko H Petkov, 2024-05-24 The Numerical Jordan Form is the first book dedicated to exploring the algorithmic and computational methods for determining the Jordan form of a matrix as well as addressing the numerical difficulties in finding it Unlike the

pure Jordan form the numerical Jordan form preserves its structure under small perturbations of the matrix elements so that its determination presents a well posed computational problem If this structure is well conditioned it can be determined reliably in the presence of uncertainties and rounding errors This book addresses the form s application in solving some important problems such as the estimation of eigenvalue sensitivity and computing the matrix exponential Special attention is paid to the Jordan Schur form of a matrix which the author suggests is not exploited sufficiently in the area of matrix computations Since the mathematical objects under consideration can be sensitive to changes in the elements of the given matrix the book also investigates the perturbation analysis of eigenvalues and invariant subspaces This study is supplemented by a collection over 100 M files suitable for MATLAB in order to implement the state of the art algorithms presented in the book for reducing a square matrix into the numerical Jordan form Researchers in the fields of numerical analysis and matrix computations and any scientists who utilise matrices in their work will find this book a useful resource and it is also a suitable reference book for graduate and advance undergraduate courses in this subject area

Matrix Tricks for Linear Statistical Models Simo Puntanen,George P. H. Styan,Jarkko Isotalo,2011-08-24 In teaching linear statistical models to first year graduate students or to final year undergraduate students there is no way to proceed smoothly without matrices and related concepts of linear algebra their use is really essential Our experience is that making some particular matrix tricks very familiar to students can substantially increase their insight into linear statistical models and also multivariate statistical analysis In matrix algebra there are handy sometimes even very simple tricks which simplify and clarify the treatment of a problem both for the student and for the professor Of course the concept of a trick is not uniquely defined by a trick we simply mean here a useful important handy result In this book we collect together our Top Twenty favourite matrix tricks for linear statistical models

On Distributed and Cooperative Control Design for Networks of Dynamical Systems Georg Seyboth,2016-06-17 This thesis contributes to the development of a cooperative control theory for homogeneous and heterogeneous multi agent systems consisting of identical and non identical dynamical agents respectively The goal is to explain fundamental effects of non identical agent dynamics on the behavior of a distributed system and primarily to develop suitable control design methods for a wide range of multi agent coordination problems Output synchronization problems as well as cooperative disturbance rejection and reference tracking problems in multi agent systems are investigated Suitable controller design methods for networks consisting of identical or non identical linear time invariant systems linear parameter varying systems and selected classes of nonlinear systems are developed These controller design methods provide a solution to a wide variety of distributed coordination and cooperative control scenarios

MIMO Radar Waveform Design for Spectrum Sharing with Cellular Systems Awais Khawar,Ahmed Abdelhadi,Charles Clancy,2016-02-13 This book discusses spectrum sharing between cellular systems and radars The book addresses a novel way to design radar waveforms that can enable spectrum sharing between radars and communication systems without

causing interference to communication systems and at the same time achieving radar objectives of target detection estimation and tracking The book includes a MATLAB based approach which provides reader with a way to learn experiment compare and build on top of existing algorithms

Cooperative Control Design He Bai,Murat Arcak,John Wen,2011-06-03 Cooperative Control Design A Systematic Passivity Based Approach discusses multi agent coordination problems including formation control attitude coordination and synchronization The goal of the book is to introduce passivity as a design tool for multi agent systems to provide exemplary work using this tool and to illustrate its advantages in designing robust cooperative control algorithms The discussion begins with an introduction to passivity and demonstrates how passivity can be used as a design tool for motion coordination Followed by the case of adaptive redesigns for reference velocity recovery while describing a basic design a modified design and the parameter convergence problem Formation control is presented as it relates to relative distance control and relative position control The coverage is concluded with a comprehensive discussion of agreement and the synchronization problem with an example using attitude coordination

Advances in Swarm Intelligence Ying Tan,Yuhui Shi,Hongwei Mo,2013-05-14 This book and its companion volume LNCS vols 7928 and 7929 constitute the proceedings of the 4th International Conference on Swarm Intelligence ICSI 2013 held in Harbin China in June 2013 The 129 revised full papers presented were carefully reviewed and selected from 268 submissions The papers are organized in 22 cohesive sections covering all major topics of swarm intelligence research and developments The following topics are covered in this volume analysis of swarm intelligence based algorithms particle swarm optimization applications of particle swarm optimization algorithms ant colony optimization algorithms biogeography based optimization algorithms novel swarm based search methods bee colony algorithms differential evolution neural networks fuzzy methods evolutionary programming and evolutionary games

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Euclidean Distance Matrices and Their Applications in Rigidity Theory Abdo Y. Alfakih, 2018-10-13 This book offers a comprehensive and accessible exposition of Euclidean Distance Matrices EDMs and rigidity theory of bar and joint frameworks It is based on the one to one correspondence between EDMs and projected Gram matrices Accordingly the machinery of semidefinite programming is a common thread that runs throughout the book As a result two parallel approaches to rigidity theory are presented The first is traditional and more intuitive approach that is based on a vector representation of point configuration The second is based on a Gram matrix representation of point configuration Euclidean Distance Matrices and Their Applications in Rigidity Theory begins by establishing the necessary background needed for the rest of the book The focus of Chapter 1 is on pertinent results from matrix theory graph theory and convexity theory while Chapter 2 is devoted to positive semidefinite PSD matrices due to the key role these matrices play in our approach Chapters 3 to 7 provide detailed studies of EDMs and in particular their various characterizations classes eigenvalues and geometry Chapter 8 serves as a transitional chapter between EDMs and rigidity theory Chapters 9 and 10 cover local and universal rigidities of bar and joint frameworks This book is self contained and should be accessible to a wide audience including

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