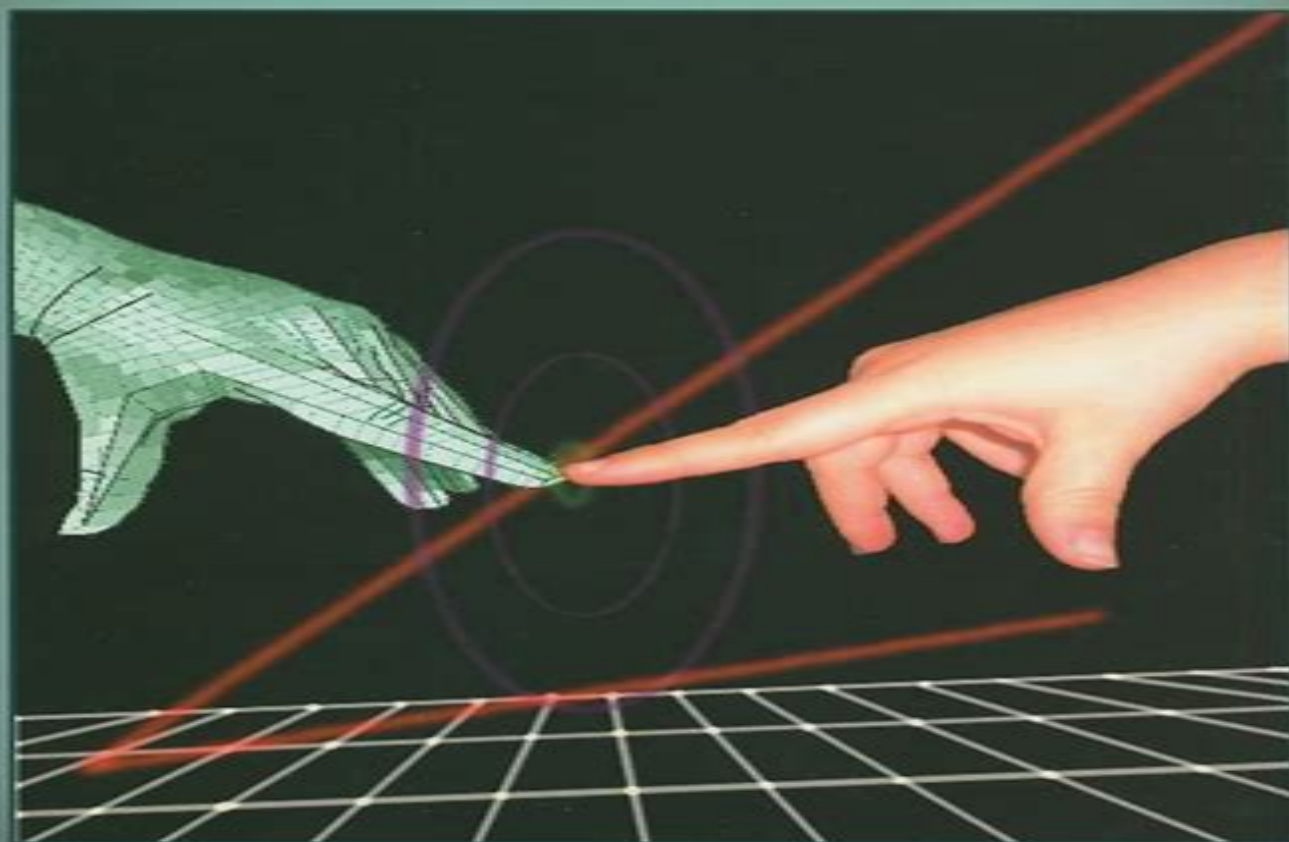


HAPTIC RENDERING

FOUNDATIONS, ALGORITHMS, AND APPLICATIONS



EDITED BY
MING C. LIN AND MIGUEL A. OTADUY

Haptic Rendering Author Ming C Lin Jul 2008

Miguel A. Otaduy



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Haptic Rendering Ming C. Lin, Miguel Otaduy, 2008-07-25 For a long time human beings have dreamed of a virtual world where it is possible to interact with synthetic entities as if they were real It has been shown that the ability to touch virtual objects increases the sense of presence in virtual environments This book provides an authoritative overview of state of the art haptic rendering algorithms

Haptic Rendering Ming C. Lin, Miguel A. Otaduy, 2008

Haptic Rendering for Simulation of Fine Manipulation Dangxiao Wang, Jing Xiao, Yuru Zhang, 2014-10-17 This book introduces the latest progress in six degrees of freedom 6 DoF haptic rendering with the focus on a new approach for simulating force torque feedback in performing tasks that require dexterous manipulation skills One of the major challenges in 6 DoF haptic rendering is to resolve the conflict between high speed and high fidelity requirements especially in simulating a tool interacting with both rigid and deformable objects in a narrow space and with fine features The book presents a configuration based optimization approach to tackle this challenge Addressing a key issue in many VR based simulation systems the book will be of particular interest to researchers and professionals in the areas of surgical simulation rehabilitation virtual assembly and inspection and maintenance

High Fidelity Haptic Rendering : Computer Graphics And Animation Miguel A. Otaduy, 2006

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