



# Human Robot Interaction In Social Robotics

**Oliver Korn**



## **Human Robot Interaction In Social Robotics:**

**Human-Robot Interaction in Social Robotics** Takayuki Kanda, Hiroshi Ishiguro, 2017-12-19 Human Robot Interaction in Social Robotics explores important issues in designing a robot system that works with people in everyday environments Edited by leading figures in the field of social robotics it draws on contributions by researchers working on the Robovie project at the ATR Intelligent Robotics and Communication Laboratories a world leader in humanoid interactive robotics The book brings together in one volume technical and empirical research that was previously scattered throughout the literature Taking a networked robot approach the book examines how robots work in cooperation with ubiquitous sensors and people over telecommunication networks It considers the use of social robots in daily life grounding the work in field studies conducted at a school train station shopping mall and science museum Critical in the development of network robots these usability studies allow researchers to discover real issues that need to be solved and to understand what kinds of services are possible The book tackles key areas where development is needed namely in sensor networks for tracking humans and robots humanoids that can work in everyday environments and functions for interacting with people It introduces a sensor network developed by the authors and discusses innovations in the Robovie humanoid including several interactive behaviors and design policies Exploring how humans interact with robots in daily life settings this book offers valuable insight into how robots may be used in the future The combination of engineering empirical and field studies provides readers with rich information to guide in developing practical interactive robots *Human-Robot Interaction and Social Robotics* Mr. Rohit Manglik, 2024-07-28 EduGorilla Publication is a trusted name in the education sector committed to empowering learners with high quality study materials and resources Specializing in competitive exams and academic support EduGorilla provides comprehensive and well structured content tailored to meet the needs of students across various streams and levels

**Social Touch in Human-Robot Interaction** Masahiro Shiomi, Hidenobu Sumioka, 2024-03-29 In this book for researchers and students editors Shiomi and Sumioka bring together contributions from researchers working on the CREST project at ATR Deep Interaction Laboratories a world leader in social robotics to comprehensively describe robot touch systems from hardware to applications Appropriate touch from robots to humans is essential for social robots but achieving this requires various solutions at every stage of the touch process Through this book readers will gain an understanding of the needs essential systems and communication cues behaviour designs and real world issues for social touch applications This book compiles and updates technical and empirical research that was previously scattered throughout the literature into a single volume Through individually authored chapters addressing various elements of ATR's CREST project this book tackles key areas where understanding is needed to realize acceptable touch interaction including pre touch interaction interaction design for touching and being touched behaviour changes caused by touch interaction and applications of social touch interaction It introduces a touch sensor and robots developed by the authors including several touch related

behaviours and design policies This approach will enable readers to easily apply this knowledge to their own social robotics programs This book is invaluable for anyone who wishes to understand and develop social robots that physically interact with people It is most beneficial for researchers and upper undergraduate and graduate students in the fields of human robot agent computer interaction and social touch interaction and those in the broader fields of engineering computer science and cognitive science

**Social Robots: Technological, Societal and Ethical Aspects of Human-Robot Interaction** Oliver Korn, 2019-07-01 Social robots not only work with humans in collaborative workspaces we meet them in shopping malls and even more personal settings like health and care Does this imply they should become more human able to interpret and adequately respond to human emotions Do we want them to help elderly people Do we want them to support us when we are old ourselves Do we want them to just clean and keep things orderly or would we accept them helping us to go to the toilet or even feed us if we suffer from Parkinson s disease The answers to these questions differ from person to person They depend on cultural background personal experiences but probably most of all on the robot in question This book covers the phenomenon of social robots from the historic roots to today s best practices and future perspectives To achieve this we used a hands on interdisciplinary approach incorporating findings from computer scientists engineers designers psychologists doctors nurses historians and many more The book also covers a vast spectrum of applications from collaborative industrial work over education to sales Especially for developments with a high societal impact like robots in health and care settings the authors discuss not only technology design and usage but also ethical aspects Thus this book creates both a compendium and a guideline helping to navigate the design space for future developments in social robotics

**What Social Robots Can and Should Do** Johanna Seibt, Søren Schack Andersen, 2016-10-14 Social robotics drives a technological revolution of possibly unprecedented disruptive potential both at the socio economic and the socio cultural level The rapid development of the robotics market calls for a concerted effort across a wide spectrum of academic disciplines to understand the transformative potential of human robot interaction This effort cannot succeed without the special expertise in the study of socio cultural interactions norms and values that humanities research provides This book contains the proceedings of the conference What Social Robots Can and Should Do Robophilosophy 2016 TRANSOR 2016 held in Aarhus Denmark in October 2016 The conference is the second event in the biennial Robophilosophy conference series this time combined with an event of the Research Network for Transdisciplinary Studies in Social Robotics TRANSOR Featuring 13 plenaries and 74 session and workshop talks the event turned out to be the world s largest conference in Humanities research in and on social robotics The book is divided into 3 sections Part I and Part III contain the abstracts of plenary lectures and contributions to 6 workshops Artificial Empathy Co Designing Children Robot Interaction Human Robot Joint Action Phronesis for Machine Ethics Robots in the Wild and Responsible Robotics Part II contains short papers for presentations in 7 thematically organized sessions methodological issues ethical tasks and implications emotions in human robot interactions education art

and innovation artificial meaning and rationality social norms and robot sociality and perceptions of social robots The book will be of interest to researchers in philosophy anthropology sociology psychology linguistics cognitive science robotics computer science and art Since all contributions are prepared for an interdisciplinary readership they are highly accessible and will be of interest to policy makers and educators who wish to gauge the challenges and potentials of putting robots in society

**Social Robots** Marco Nørskov, 2017-07-05 Social robotics is a cutting edge research area gathering researchers and stakeholders from various disciplines and organizations The transformational potential that these machines in the form of for example caregiving entertainment or partner robots pose to our societies and to us as individuals seems to be limited by our technical limitations and phantasy alone This collection contributes to the field of social robotics by exploring its boundaries from a philosophically informed standpoint It constructively outlines central potentials and challenges and thereby also provides a stable fundament for further research of empirical qualitative or methodological nature

*Human-Robot Interaction* Daisuke Chugo, 2010-02-01 Human robot interaction HRI is the study of interactions between people users and robots HRI is multidisciplinary with contributions from the fields of human computer interaction artificial intelligence robotics speech recognition and social sciences psychology cognitive science anthropology and human factors There has been a great deal of work done in the area of human robot interaction to understand how a human interacts with a computer However there has been very little work done in understanding how people interact with robots For robots becoming our friends these studies will be required more and more

Human-Robot Interaction Christoph Bartneck, Tony Belpaeme, Friederike Eyssel, Takayuki Kanda, Merel Keijsers, Selma Šabanović, 2024-06-27 The role of robots in society keeps expanding and diversifying bringing with it a host of issues surrounding the relationship between robots and humans This introduction to human robot interaction HRI by leading researchers in this developing field is the first to provide a broad overview of the multidisciplinary topics central to modern HRI research Written for students and researchers from robotics artificial intelligence psychology sociology and design it presents the basics of how robots work how to design them and how to evaluate their performance Self contained chapters discuss a wide range of topics including speech and language nonverbal communication and processing emotions plus an array of applications and the ethical issues surrounding them This revised and expanded second edition includes a new chapter on how people perceive robots coverage of recent developments in robotic hardware software and artificial intelligence and exercises for readers to test their knowledge

Sociality and Normativity for Robots Raul Hakli, Johanna Seibt, 2017-05-30 This volume offers eleven philosophical investigations into our future relations with social robots robots that are specially designed to engage and connect with human beings The contributors present cutting edge research that examines whether and on which terms robots can become members of human societies Can our relations to robots be said to be social Can robots enter into normative relationships with human beings How will human social relations change when we interact with robots at work and at home The authors of

this volume explore these questions from the perspective of philosophy cognitive science psychology and robotics The first three chapters offer a taxonomy for the classification of simulated social interactions investigate whether human social interactions with robots can be genuine and discuss the significance of social relations for the formation of human individuality Subsequent chapters clarify whether robots could be said to actually follow social norms whether they could live up to the social meaning of care in caregiving professions and how we will need to program robots so that they can negotiate the conventions of human social space and collaborate with humans Can we perform joint actions with robots where both sides need to honour commitments and how will such new commitments and practices change our regional cultures The authors connect research in social robotics and empirical studies in Human Robot Interaction to recent debates in social ontology social cognition as well as ethics and philosophy of technology The book is a response to the challenge that social robotics presents for our traditional conceptions of social interaction which presuppose such essential capacities as consciousness intentionality agency and normative understanding The authors develop insightful answers along new interdisciplinary pathways in robophilosophy a new research area that will help us to shape the robot revolution the distinctive technological change of the beginning 21st century      Social Robotics Abderrahmane Kheddar, Eiichi Yoshida, Shuzhi Sam Ge, Kenji Suzuki, John-John Cabibihan, Friederike Eyssel, Hongsheng He, 2017-11-13 This book constitutes the refereed proceedings of the 9th International Conference on Social Robotics ICSR 2016 held in Tsukuba Japan in November 2017 The 74 revised full papers presented were carefully reviewed and selected from 110 submissions The theme of the 2017 conference is Embodied Interactive Robots In addition to the technical sessions ICSR 2017 included four workshops 1 Social Robot Intelligence for Social Human Robot Interaction of Service Robots 2 Human Safety and Comfort in Human Robot Interactive Social Environments 3 Modes of Interaction for Social Robots MISR 2017 Postures Gestures and Microinteractions and 4 Religion in Robotics      **Social Robotics** Miguel A. Salichs, Shuzhi Sam Ge, Emilia Ivanova Barakova, John-John Cabibihan, Alan R. Wagner, Álvaro Castro-González, Hongsheng He, 2019-11-21 This book constitutes the refereed proceedings of the 11th International Conference on Social Robotics ICSR 2019 held in Madrid Spain in November 2019 The 69 full papers presented were carefully reviewed and selected from 92 submissions The theme of the 2018 conference is Friendly Robotics The papers focus on the following topics perceptions and expectations of social robots cognition and social values for social robots verbal interaction with social robots social cues and design of social robots emotional and expressive interaction with social robots collaborative SR and SR at the workplace game approaches and applications to HRI applications in health domain robots at home and at public spaces robots in education technical innovations in social robotics and privacy and safety of the social robots      *Social Robotics* Alan R. Wagner, David Feil-Seifer, Kerstin S. Haring, Silvia Rossi, Thomas Williams, Hongsheng He, Shuzhi Sam Ge, 2020-11-07 This book constitutes the refereed proceedings of the 12th International Conference on Social Robotics ICSR 2020 held in Golden CO USA in

November 2020 The conference was held virtually The 57 full papers presented were carefully reviewed and selected from 101 submissions The theme of the 2020 conference is Entertaining Robots The papers focus on the following topics human robot trust and human robot teaming robot understanding and following of social and moral norms physical and interaction design of social robots verbal and nonverbal robot communication interactive robot learning robot motion and proxemics and robots in domains such as education and healthcare

**Human-Robot Interaction** Céline Jost, Brigitte Le Pévédic, Tony Belpaeme, Cindy Bethel, Dimitrios Chrysostomou, Nigel Crook, Marine Grandgeorge, Nicole Mirnig, 2020-05-13 This book offers the first comprehensive yet critical overview of methods used to evaluate interaction between humans and social robots It reviews commonly used evaluation methods and shows that they are not always suitable for this purpose Using representative case studies the book identifies good and bad practices for evaluating human robot interactions and proposes new standardized processes as well as recommendations carefully developed on the basis of intensive discussions between specialists in various HRI related disciplines e g psychology ethology ergonomics sociology ethnography robotics and computer science The book is the result of a close long standing collaboration between the editors and the invited contributors including but not limited to their inspiring discussions at the workshop on Evaluation Methods Standardization for Human Robot Interaction EMSHRI which have been organized yearly since 2015 By highlighting and weighing good and bad practices in evaluation design for HRI the book will stimulate the scientific community to search for better solutions take advantages of interdisciplinary collaborations and encourage the development of new standards to accommodate the growing presence of robots in the day to day and social lives of human beings

Social Robotics Arvin Agah, John-John Cabibihan, Ayanna M. Howard, Miguel A. Salichs, Hongsheng He, 2016-10-06 This book constitutes the refereed proceedings of the 8th International Conference on Social Robotics ICSR 2016 held in Kansas City MO USA in November 2016 The 98 revised full papers presented were carefully reviewed and selected from 107 submissions The theme of the 2016 conference is Sociorobotics Design and implementation of social behaviors of robots interacting with each other and humans In addition to technical sessions ICSR 2016 included three workshops The Synthetic Method in Social Robotics SMSR 2016 Social Robots A Tool to Advance Interventions for Autism and Using Social Robots to Improve the Quality of Life in the Elderly

*Social robots : technological, societal and ethical aspects of human-robot interaction*, 2019 Social robots not only work with humans in collaborative workspaces we meet them in shopping malls and even more personal settings like health and care Does this imply they should become more human able to interpret and adequately respond to human emotions Do we want them to help elderly persons Do we want them to support us when we are old ourselves Do we want them to just clean and keep things orderly or would we accept them helping us to go to the toilet or even feed us if we suffer from Parkinson s disease The answers to these questions differ from person to person They depend on cultural background personal experiences but probably most of all on the robot in question This book covers the phenomenon of social robots from the

historic roots to today's best practices and future perspectives To achieve this we used a hands on interdisciplinary approach incorporating findings from computer scientists engineers designers psychologists doctors nurses historians and many more The book also covers a vast spectrum of applications from collaborative industrial work over education to sales Especially for developments with a high societal impact like robots in health and care settings the authors discuss not only technology design and usage but also ethical aspects Thus this book creates both a compendium and a guideline helping to navigate the design space for future developments in social robotics

**Social Robotics** Guido Herrmann, Martin Pearson, Alexander Lenz, Paul Bremner, Adam Spiers, Ute Leonards, 2013-10-23 This book constitutes the refereed proceedings of the 5th International Conference on Social Robotics ICSR 2013 held in Bristol UK in October 2013 The 55 revised full papers and 13 abstracts were carefully reviewed and selected from 108 submissions and are presented together with one invited paper The papers cover topics such as human robot interaction child development and care for the elderly as well as technical issues underlying social robotics visual attention and processing motor control and learning

*Social Robotics* Michael Beetz, Benjamin Johnston, Mary-Anne Williams, 2014-10-17 This book constitutes the refereed proceedings of the 6th International Conference on Social Robotics ICSR 2014 held in Sydney NSW Australia in October 2014 The 41 revised full papers presented in this book were carefully reviewed and selected from numerous submissions Amongst others topics covered are such as interaction and collaboration among robots humans and environments robots to assist the elderly and persons with disabilities socially assistive robots to improve quality of life affective and cognitive sciences for socially interactive robots personal robots for the home social acceptance and impact in the society robot ethics in human society and legal implications context awareness expectation and intention understanding control architectures for social robotics socially appealing design methodologies safety in robots working in human spaces human augmentation rehabilitation and medical robots robot applications in education entertainment and gaming knowledge representation and reasoning frameworks for robot social intelligence cognitive architectures that support social intelligence for robots robots in the workplace human robot interaction creative and entertaining robots

**Social Touch in Human-Robot Interaction** Masahiro Shiomi, Hidenobu Sumioka, 2024-03 In this book for researchers and students editors Shiomi and Sumioka bring together contributions from researchers working on the CREST project at ATR Deep Interaction Laboratories a world leader in social robotics to comprehensively describe robot touch systems from hardware to applications Appropriate touch from robots to humans is essential for social robots but achieving this requires various solutions at every stage of the touch process Through this book readers will gain an understanding of the needs essential systems and communication cues behaviour designs and real world issues for social touch applications This book compiles and updates technical and empirical research that was previously scattered throughout the literature into a single volume Through individually authored chapters addressing various elements of ATR's CREST project this book tackles key areas where understanding is needed to realize



acceptable touch interaction including pre touch interaction interaction design for touching and being touched behaviour changes caused by touch interaction and applications of social touch interaction It introduces a touch sensor and robots developed by the authors including several touch related behaviours and design policies This approach will enable readers to easily apply this knowledge to their own social robotics programs This book is invaluable for anyone who wishes to understand and develop social robots that physically interact with people It is most beneficial for researchers and upper undergraduate and graduate students in the fields of human robot agent computer interaction and social touch interaction and those in the broader fields of engineering computer science and cognitive science      Social Robotics Haizhou

Li,John-John Cabibihan,Yeow Kee Tan,2010-11-02 The papers in this volume were the fruitful scientific results of the Second International Conference on Social Robotics ICSR held during November 23 24 2010 in Singapore which was jointly organized by the Social Robotics Laboratory SRL Interactive Digital Media Institute IDMI the National University of Singapore and 2 Human Language Technology Department the Institute for Infocomm Research I R A STAR Singapore These papers address a range of topics in social robotics and its applications We received paper submissions from America Asia and Europe All the papers were reviewed by at least three referees from the 32 member Program Committee who were assembled from the global community of social robotics researchers This v ume contains the 42 papers that were selected to report on the latest developments and studies of social robotics in the areas of human robot interaction affective and cognitive sciences for interactive robots design philosophies and software archit tures for robots learning adaptation and evolution of robotic intelligence and mec tronics and intelligent control      *Social Robotics* Adriana Tapus,Elisabeth André,Jean-Claude Martin,François Ferland,Mehdi Ammi,2015-10-27 This book constitutes the refereed proceedings of the 7th International Conference on Social Robotics ICSR 2015 held in Paris France in October 2015 The 70 revised full papers presented were carefully reviewed and selected from 126 submissions The papers focus on the interaction between humans and robots and the integration of robots into our society and present innovative ideas and concepts new discoveries and improvements novel applications on the latest fundamental advances in the core technologies that form the backbone of social robotics distinguished developmental projects as well as seminal works in aesthetic design ethics and philosophy studies on social impact and influence pertaining to social robotics and its interaction and communication with human beings and its social impact on our society

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## **Table of Contents Human Robot Interaction In Social Robotics**

1. Understanding the eBook Human Robot Interaction In Social Robotics
  - The Rise of Digital Reading Human Robot Interaction In Social Robotics
  - Advantages of eBooks Over Traditional Books
2. Identifying Human Robot Interaction In Social Robotics
  - Exploring Different Genres
  - Considering Fiction vs. Non-Fiction
  - Determining Your Reading Goals
3. Choosing the Right eBook Platform
  - Popular eBook Platforms
  - Features to Look for in an Human Robot Interaction In Social Robotics
  - User-Friendly Interface
4. Exploring eBook Recommendations from Human Robot Interaction In Social Robotics
  - Personalized Recommendations
  - Human Robot Interaction In Social Robotics User Reviews and Ratings
  - Human Robot Interaction In Social Robotics and Bestseller Lists

5. Accessing Human Robot Interaction In Social Robotics Free and Paid eBooks
  - Human Robot Interaction In Social Robotics Public Domain eBooks
  - Human Robot Interaction In Social Robotics eBook Subscription Services
  - Human Robot Interaction In Social Robotics Budget-Friendly Options
6. Navigating Human Robot Interaction In Social Robotics eBook Formats
  - ePub, PDF, MOBI, and More
  - Human Robot Interaction In Social Robotics Compatibility with Devices
  - Human Robot Interaction In Social Robotics Enhanced eBook Features
7. Enhancing Your Reading Experience
  - Adjustable Fonts and Text Sizes of Human Robot Interaction In Social Robotics
  - Highlighting and Note-Taking Human Robot Interaction In Social Robotics
  - Interactive Elements Human Robot Interaction In Social Robotics
8. Staying Engaged with Human Robot Interaction In Social Robotics
  - Joining Online Reading Communities
  - Participating in Virtual Book Clubs
  - Following Authors and Publishers Human Robot Interaction In Social Robotics
9. Balancing eBooks and Physical Books Human Robot Interaction In Social Robotics
  - Benefits of a Digital Library
  - Creating a Diverse Reading Collection Human Robot Interaction In Social Robotics
10. Overcoming Reading Challenges
  - Dealing with Digital Eye Strain
  - Minimizing Distractions
  - Managing Screen Time
11. Cultivating a Reading Routine Human Robot Interaction In Social Robotics
  - Setting Reading Goals Human Robot Interaction In Social Robotics
  - Carving Out Dedicated Reading Time
12. Sourcing Reliable Information of Human Robot Interaction In Social Robotics
  - Fact-Checking eBook Content of Human Robot Interaction In Social Robotics
  - Distinguishing Credible Sources
13. Promoting Lifelong Learning

- Utilizing eBooks for Skill Development
- Exploring Educational eBooks

### 14. Embracing eBook Trends

- Integration of Multimedia Elements
- Interactive and Gamified eBooks

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web our intuitive definition of force that is a push or a pull is a good place to start we know that a push or pull has both magnitude and direction therefore it is a vector quantity and can vary considerably in each regard for example a cannon exerts a strong force on a cannonball that is launched into the air

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web jan 14 2013 class date momentum 1 a moving car has momentum if it moves twice as fast its momentum is twice as much 2 two cars one twice as heavy as the other move down a hill at the same speed compared to the lighter car the momentum of the heavier car is twice as much 3 the recoil momentum of a cannon that kicks is

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web the locomotives of india presently consist of electric and diesel locomotives steam locomotives are no longer used in india except in heritage trains a locomotive is also called loco or engine the bengal sappers of the indian army were the first to run a steam locomotive in india

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web this article lists the diesel locomotives that have operated or are operating on indian railways classification edit

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web the indian locomotive class wdm 2 is a class of diesel electric locomotive that was developed in 1962 by american locomotive company alco for indian railways the model name stands for broad gauge w diesel d mixed traffic m engine 2nd generation 2 they entered service in 1962

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web general motor diesel locomotive i preface the gm locomotives have been included in the diesel locomotive fleet of indian railway production of gm locomotive has already started in dlw varanasi

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web feb 11 2017 diesel locomotives of indian railways a technical history joydeep dutta avinash kumar agarwal chapter first online 11 february 2017 abstract in this article we would like to trace the history of the growth of diesel traction of indian railways without completely sacrificing technical details

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web indian railways manufactures its diesel locomotives at diesel locomotive works dlw a premier production unit working

under the ministry of indian railways the above unit was established in 1961 in collaboration with m s american locomotive company alco usa at varanasi the oldest living city of human civilization since

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web the objective of this block is to make you understand about the major components of the diesel engine as per the following details construction manufacturing process salient features and required dimensional accuracy in the key areas assembling technique and their inspection procedure failure analysis of components structure introduction

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web the banaras locomotive works blw formerly diesel locomotive works dlw in varanasi india is a production unit of indian railways dlw stopped manufacturing diesel locomotives in march 2019 and was renamed blw in oct 2020 2 history founded in 1961 as the dlw it rolled out its first locomotive three years later on 3 january 1964

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web diesel locomotives were introduced in indian railways in late 1950s when first lot of diesel locomotives was imported from m s alco usa with the setting up of diesel locomotive works dlw at varanasi in the year 1961 the additions to diesel locomotive fleet started at a regular pace

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web in the year 1957 indian railways imported its first mainline diesel locomotive from the american locomotive company alco in new york and classified it as wdm1 the wdm1 17000 was the first locomotive of the class after which about one hundred of these locomotives were imported in india for operation in the eastern and south eastern

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web the alco dl560c is a series of diesel electric locomotive with ac electric transmission designed by the american locomotive company and produced under license by banaras locomotive works blw varanasi india for indian railways as their classes wdm 2 wdm 3a 2c wdm 3d and wdg 3a for operation in india

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web the indian railways primarily operates a fleet of electric and diesel locomotives along with several compressed natural gas cng locomotives steam locomotives are operated on a few world heritage sites and also run occasionally as heritage trains a locomotive is also known as a loco or more popularly as an engine

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