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of spot welding guns with
KUKA robot controller

Kuka Spot Manual

Scott C. Dulebohn



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reflected of these objects into an image and processing that image Robot vision makes use of computers or other electronic hardware to analyze visual images and recognize objects of importance in the current application of the robots Digital image is an array of pixels that has been digitized into the memory of a computer A binary number is stored in each pixel to represent the intensity and possibly the wavelength of the light falling on the part of the image Robot vision is the system including different methods for processing analyzing and understanding the visuals interpreted by a robot All these methods produce information that is translated into decisions for robots From start to capture images and to the final decision of the robot a wide range of technologies and algorithms are used like a committee of filtering and decisions A Robot vision system has to make the distinction between objects and in almost all cases has to tracking these objects Applied in the real world for Robot applications these vision systems are designed to duplicate the capabilities of the human vision system using programming code and electronic parts As human eyes can detect and track many objects in the same time Robot vision systems seem to pass the difficulty in detecting and tracking many objects at the same time A Robot system finds its place in many fields from industry and Robot services Even is used for identification or navigation these systems are under continuing advances with new features like 3D support filtering or detection of light intensity applied to an object Applications and benefits for Robot vision systems used in industry or for service robots includes

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